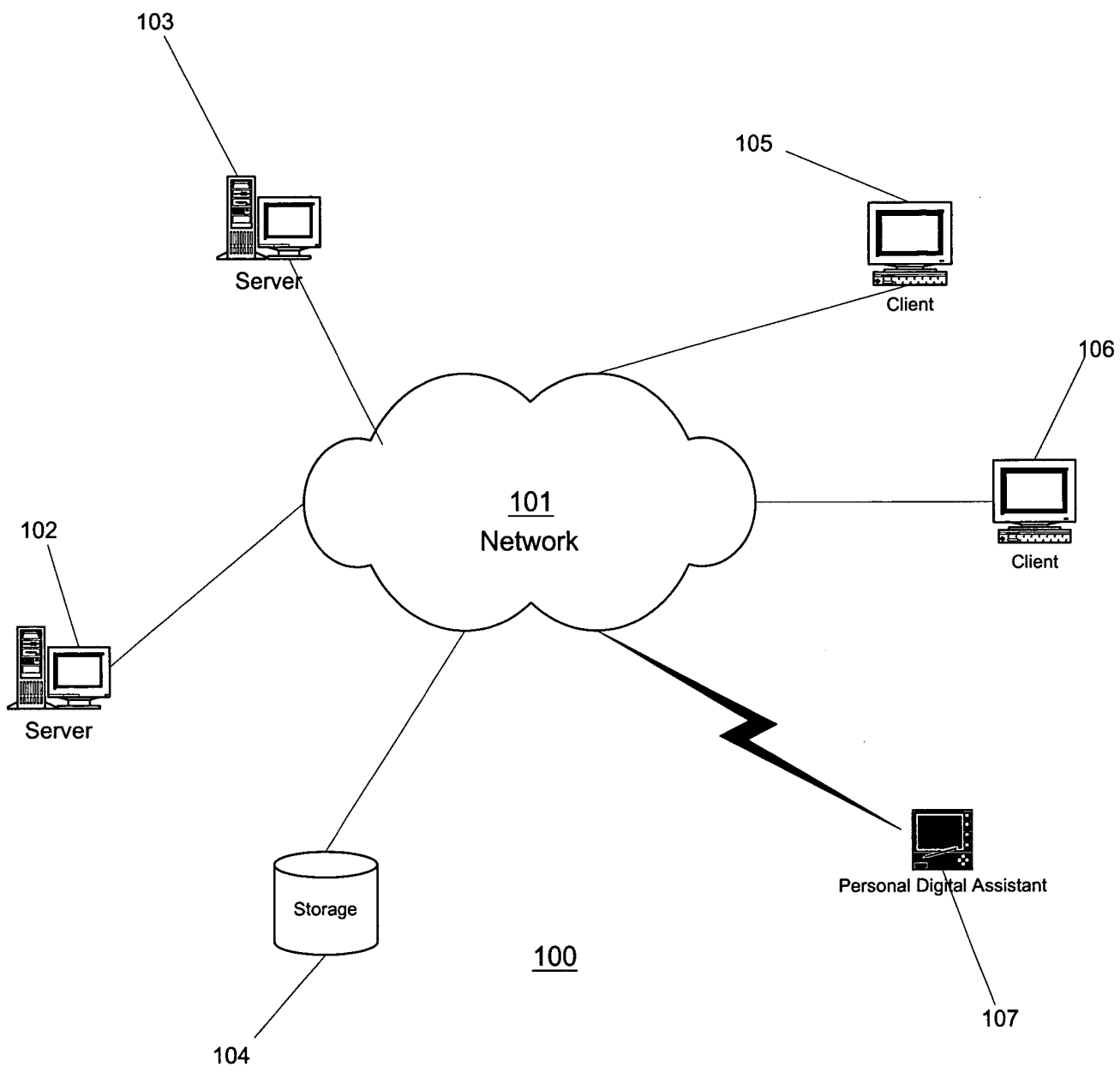
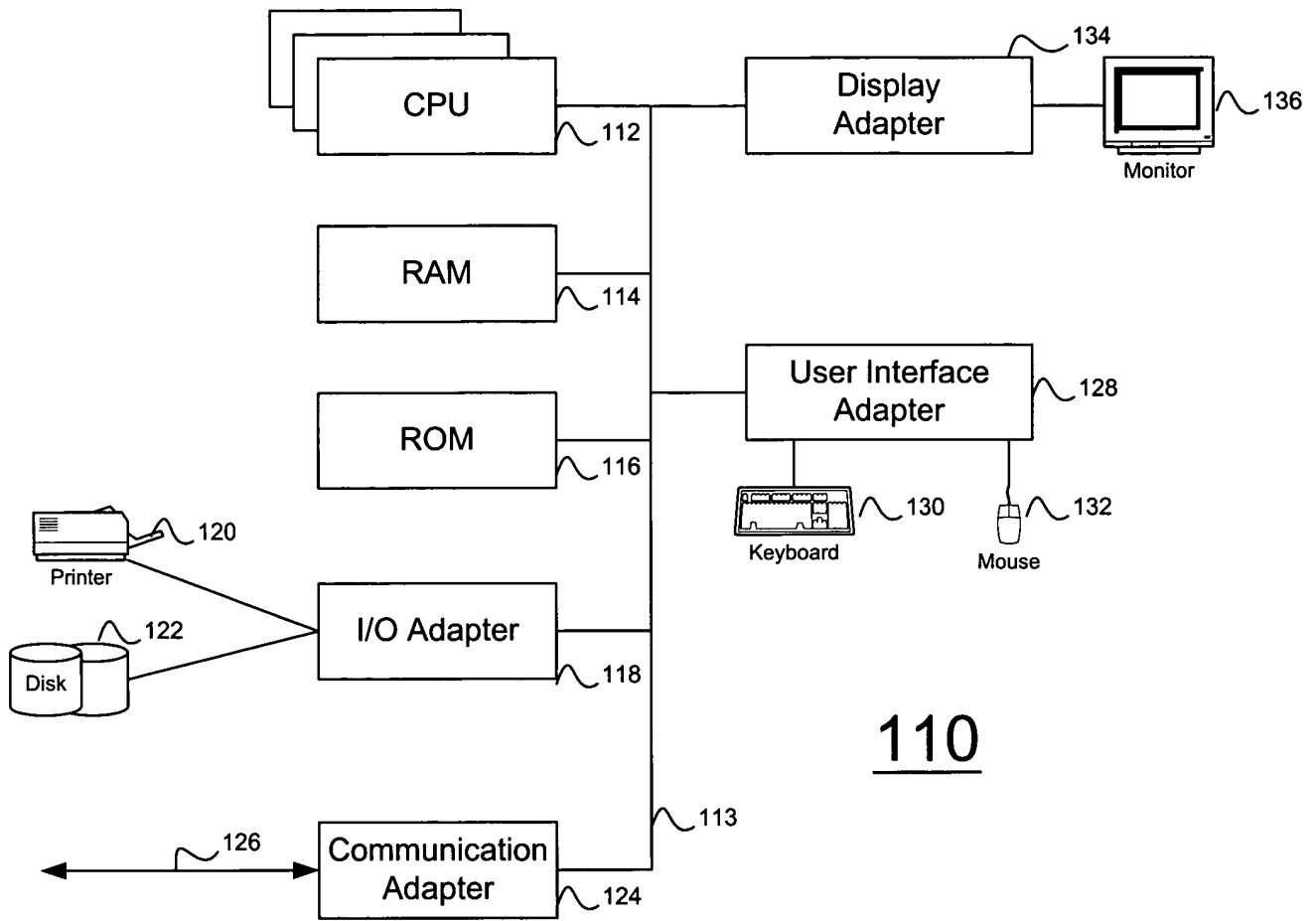


004060" 6TT 25960



Prior Art
Figure 1A

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Prior Art
Figure 1B

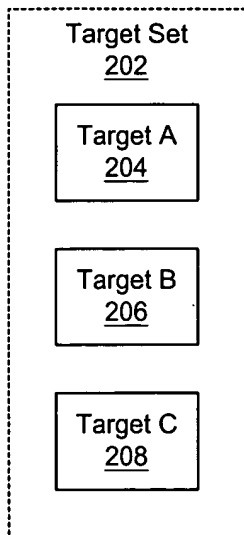


Figure 2A
Prior Art

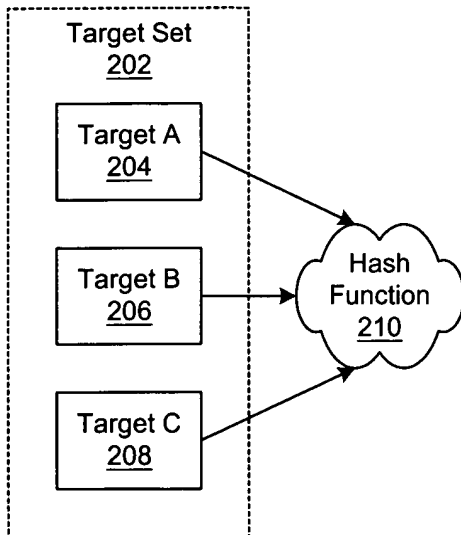


Figure 2B
Prior Art

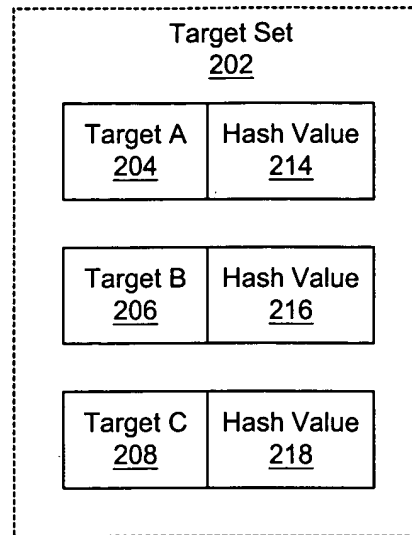


Figure 2C
Prior Art

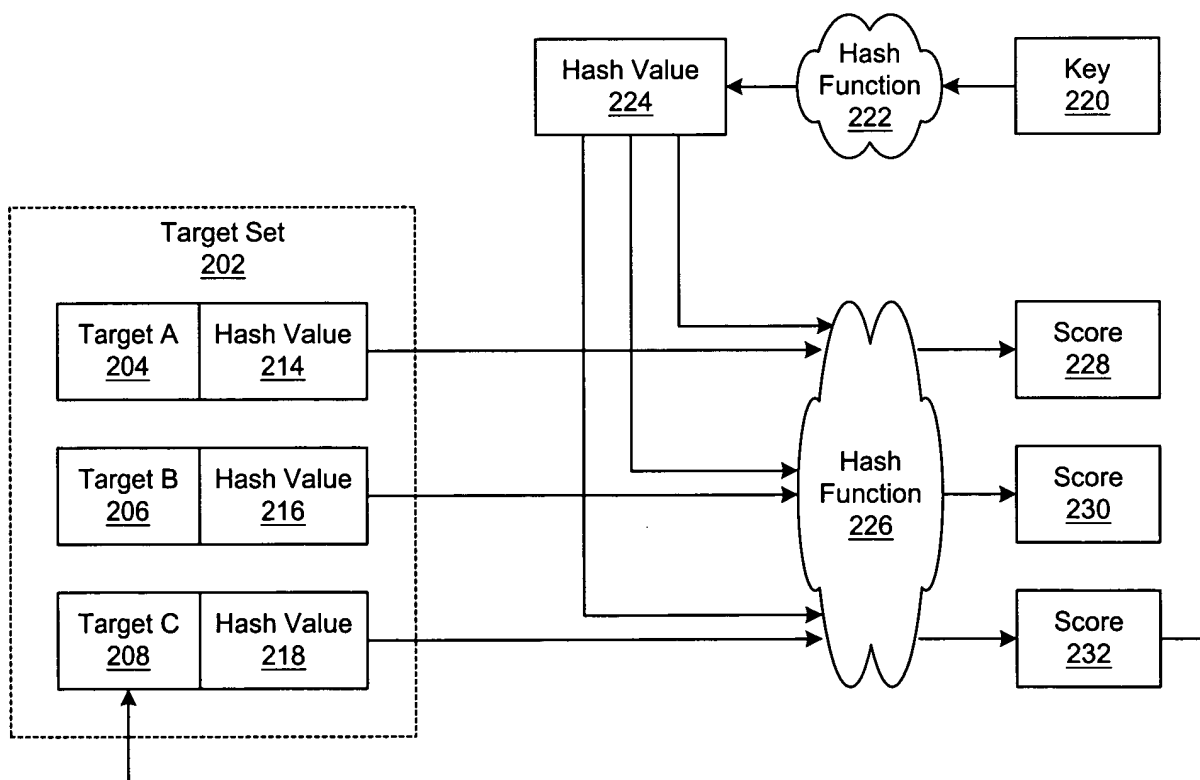


Figure 2D
Prior Art

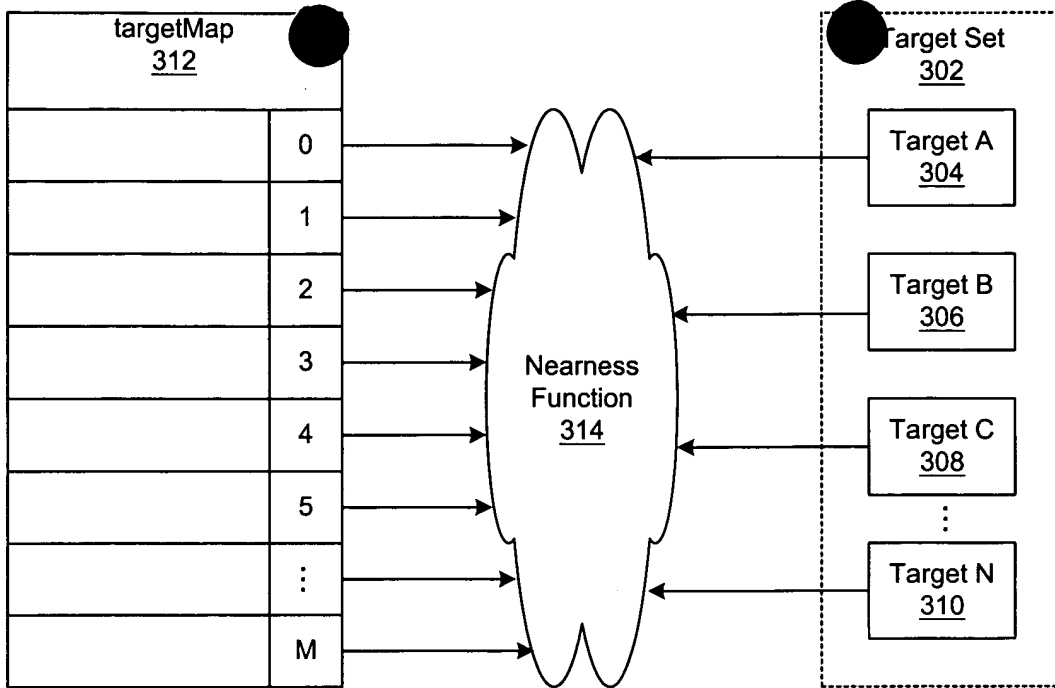


Figure 3A

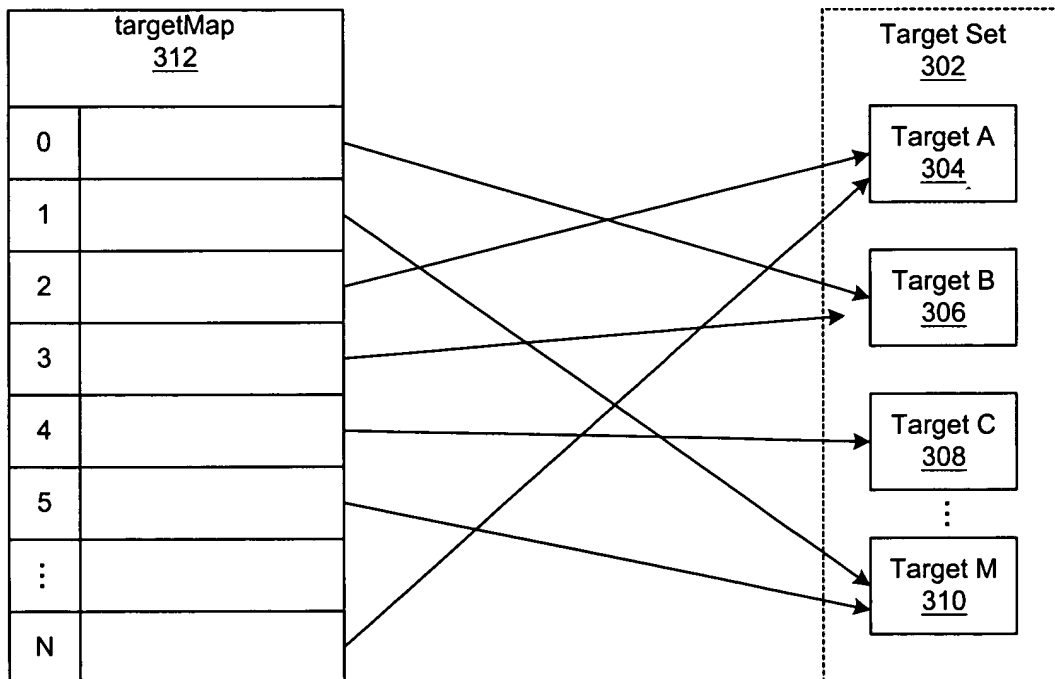


Figure 3B

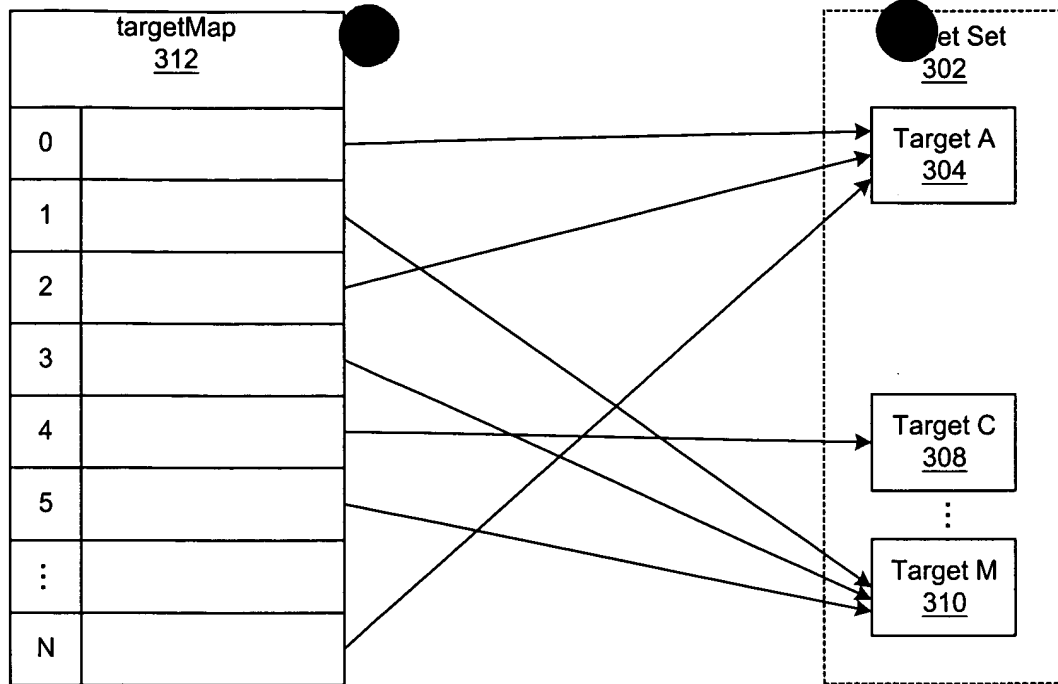


Figure 3C

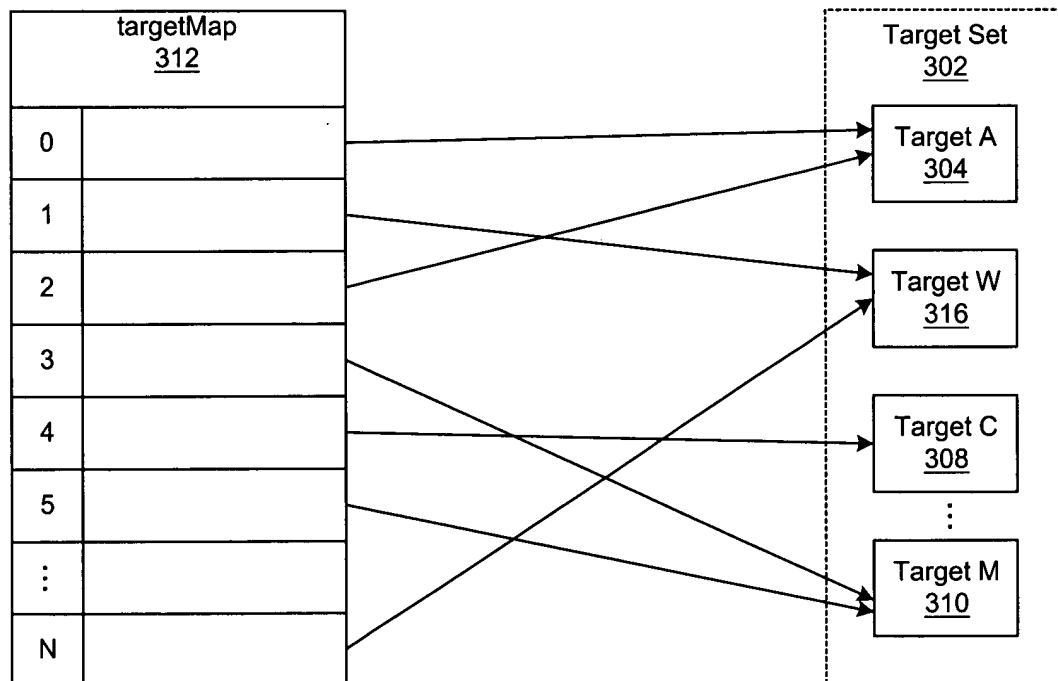


Figure 3D

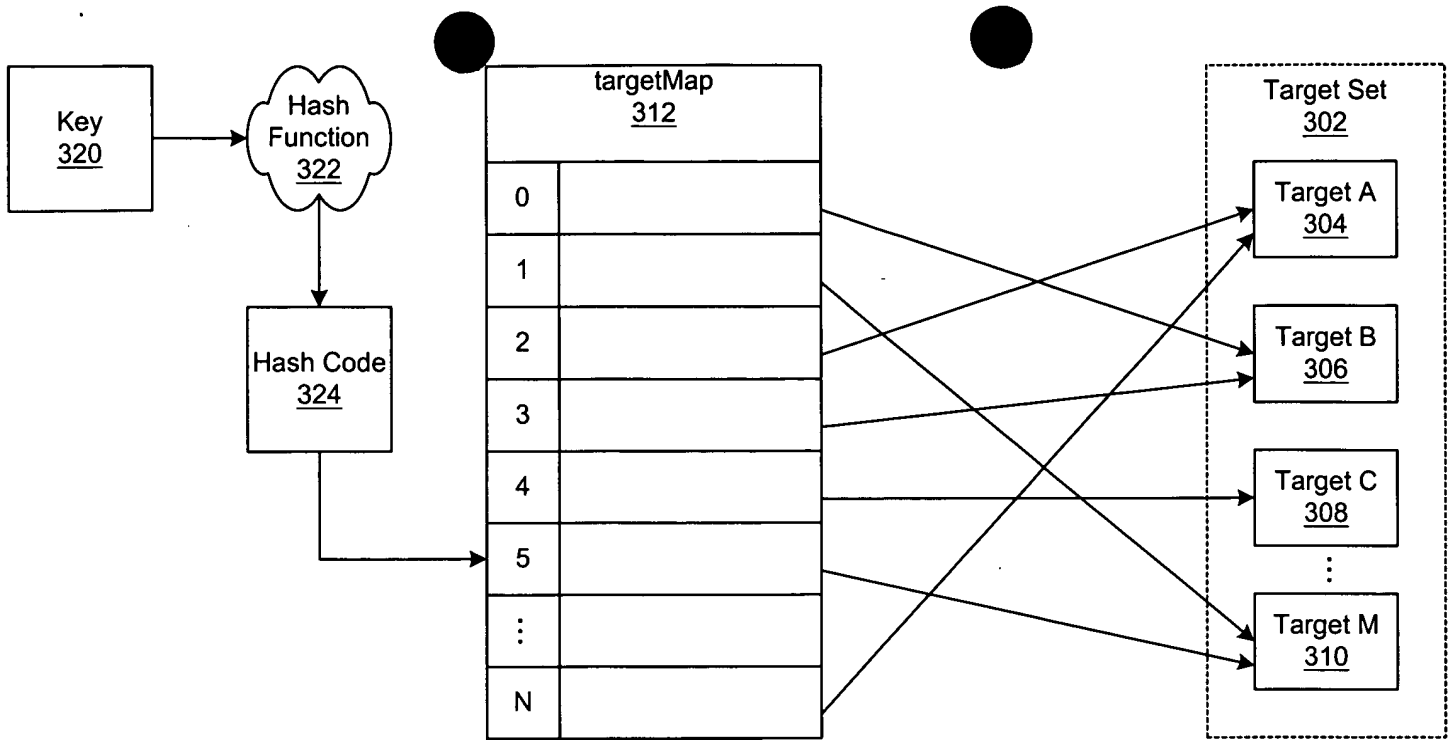


Figure 3E

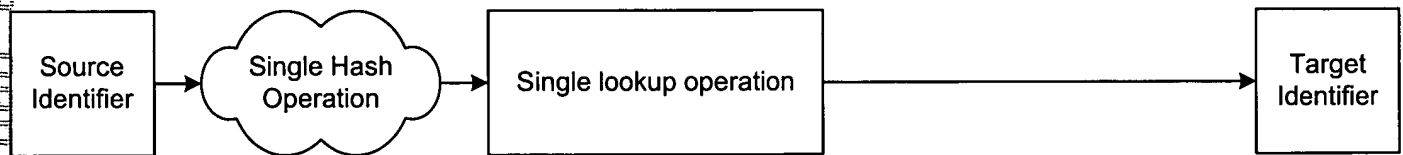


Figure 3F

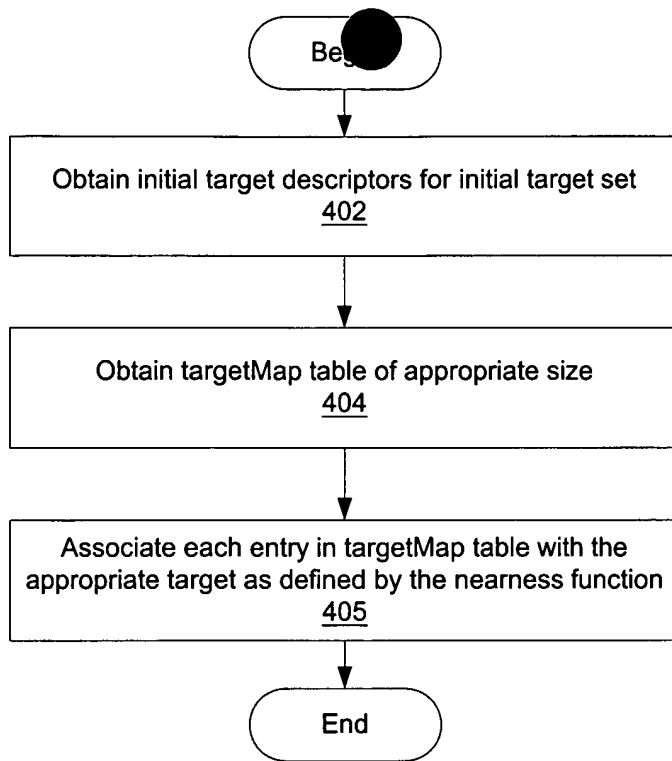


Figure 4A

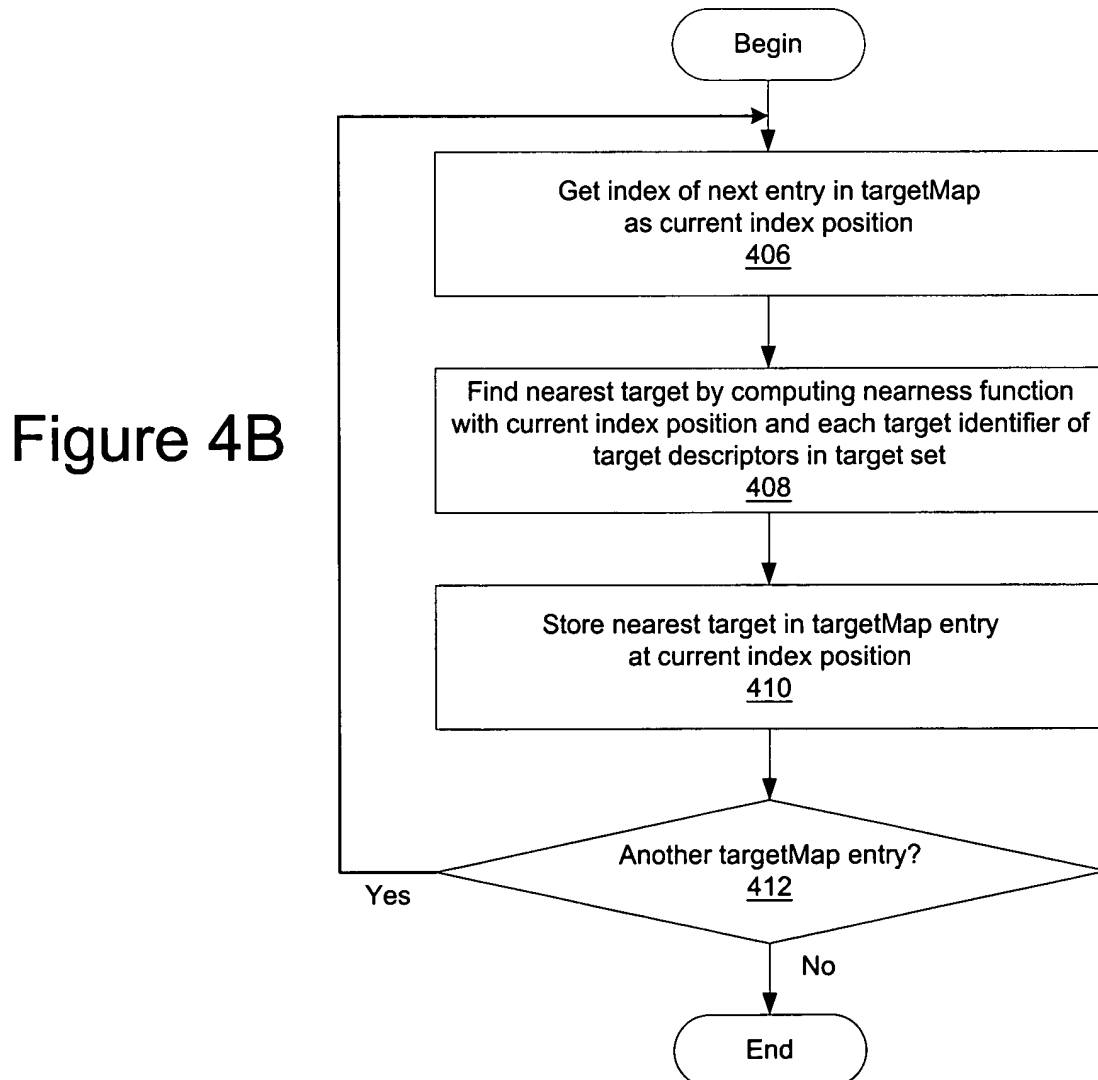


Figure 4B

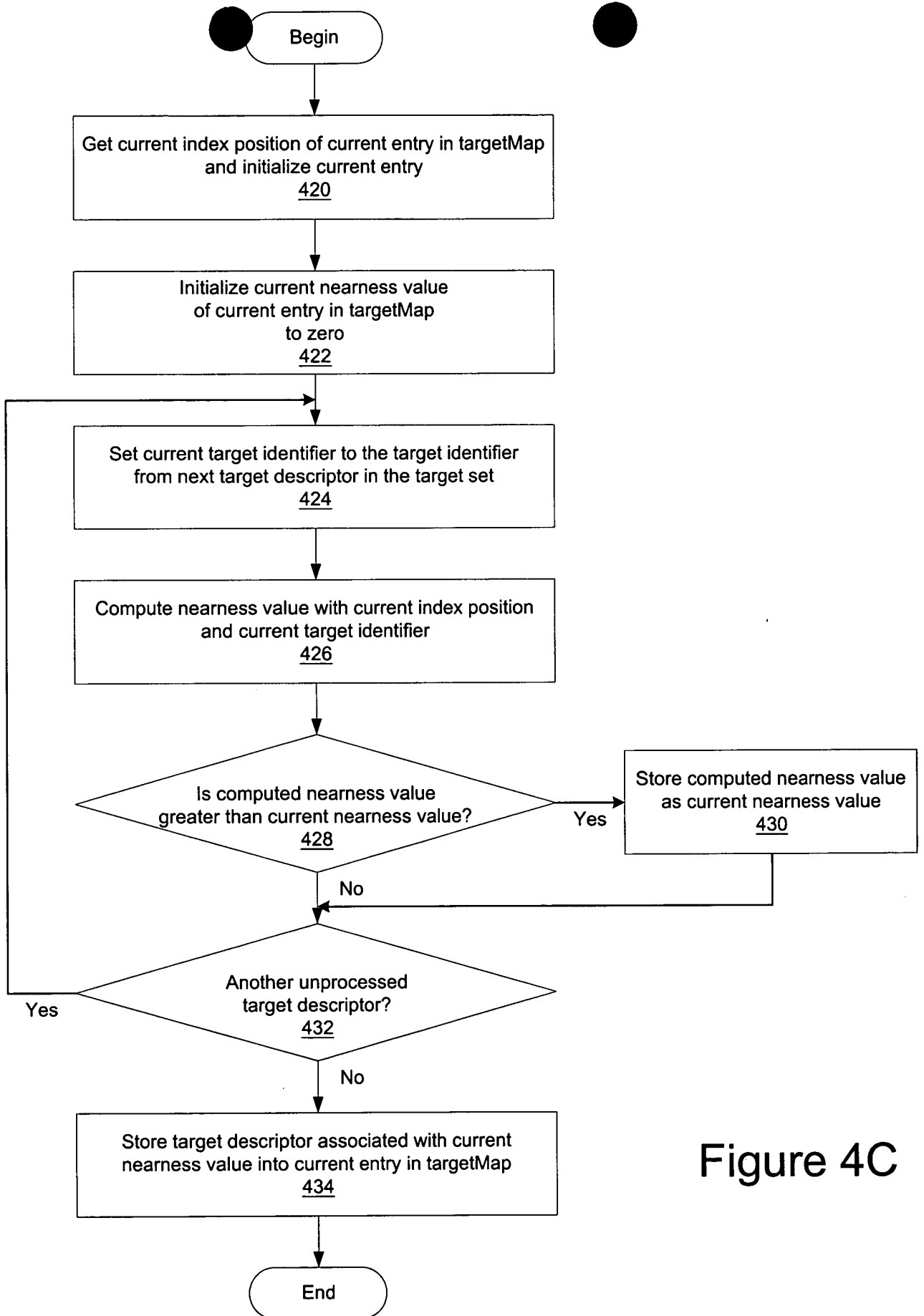


Figure 4C

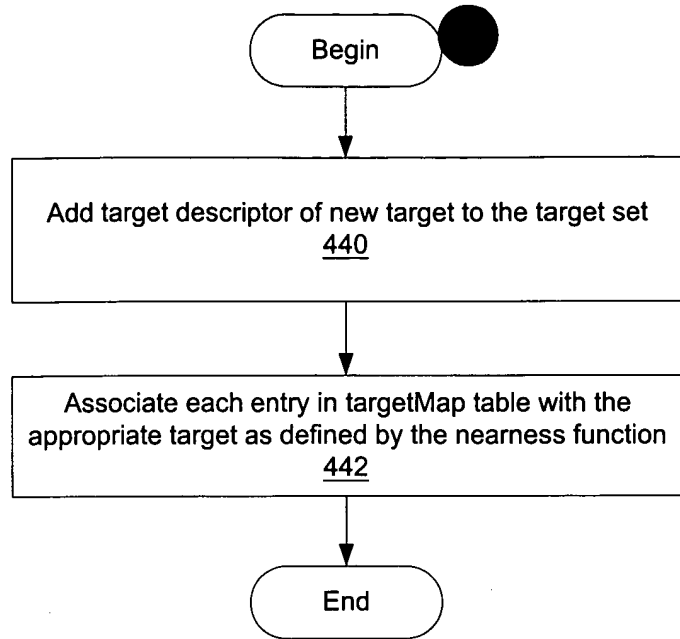


Figure 4D

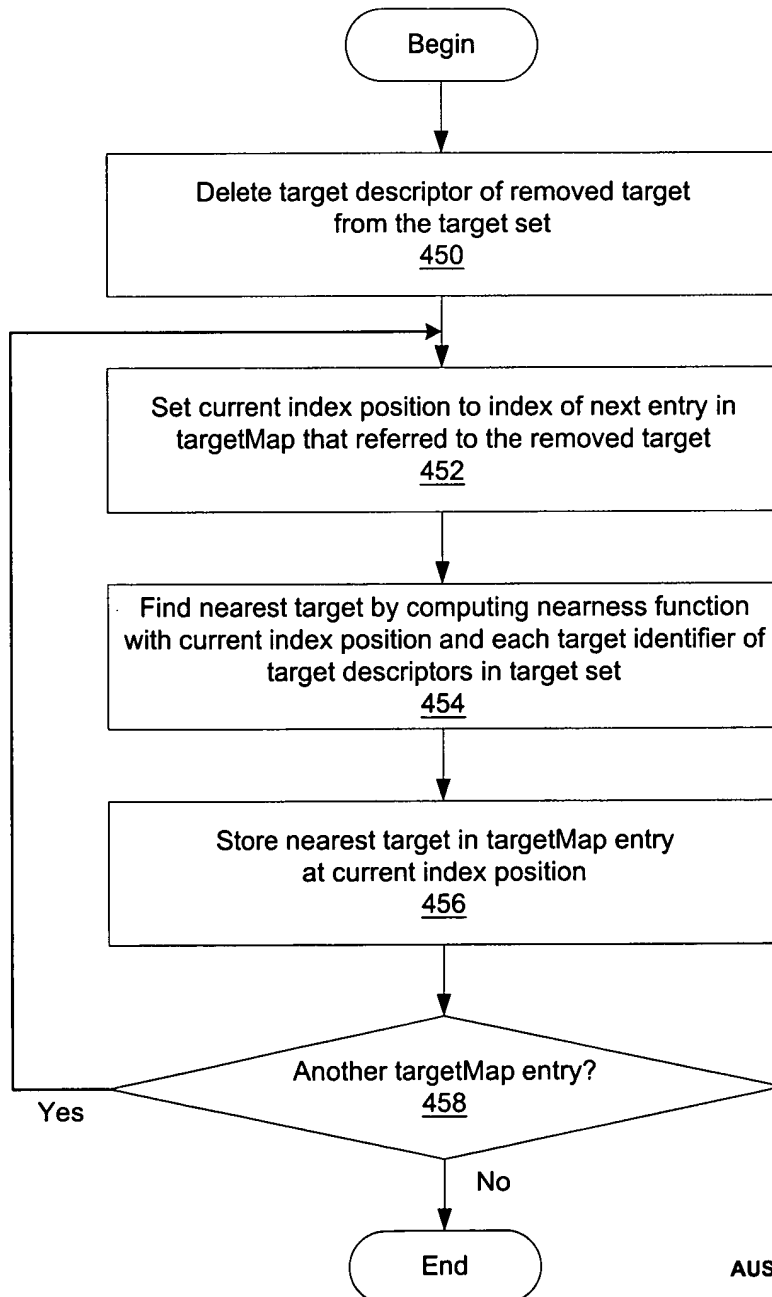


Figure 4E

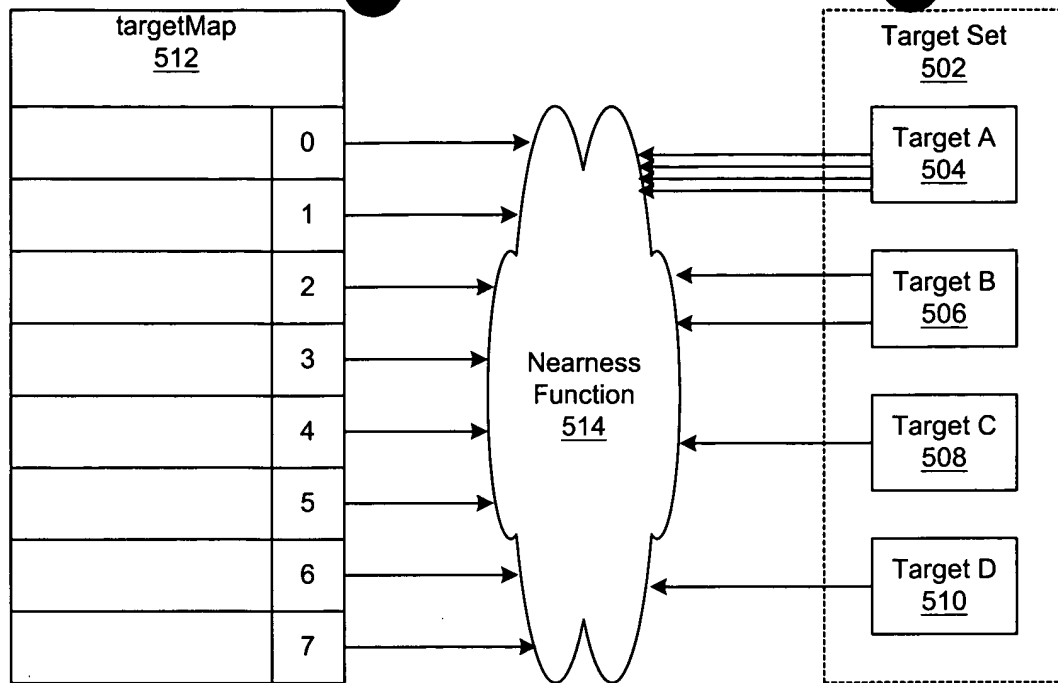


Figure 5A

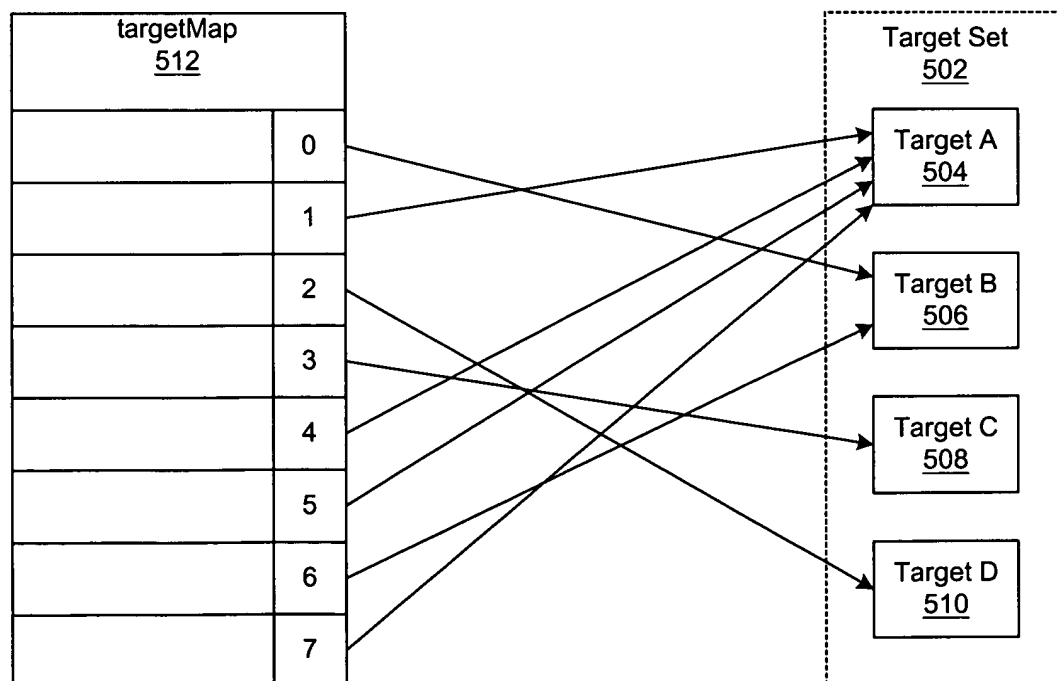


Figure 5B

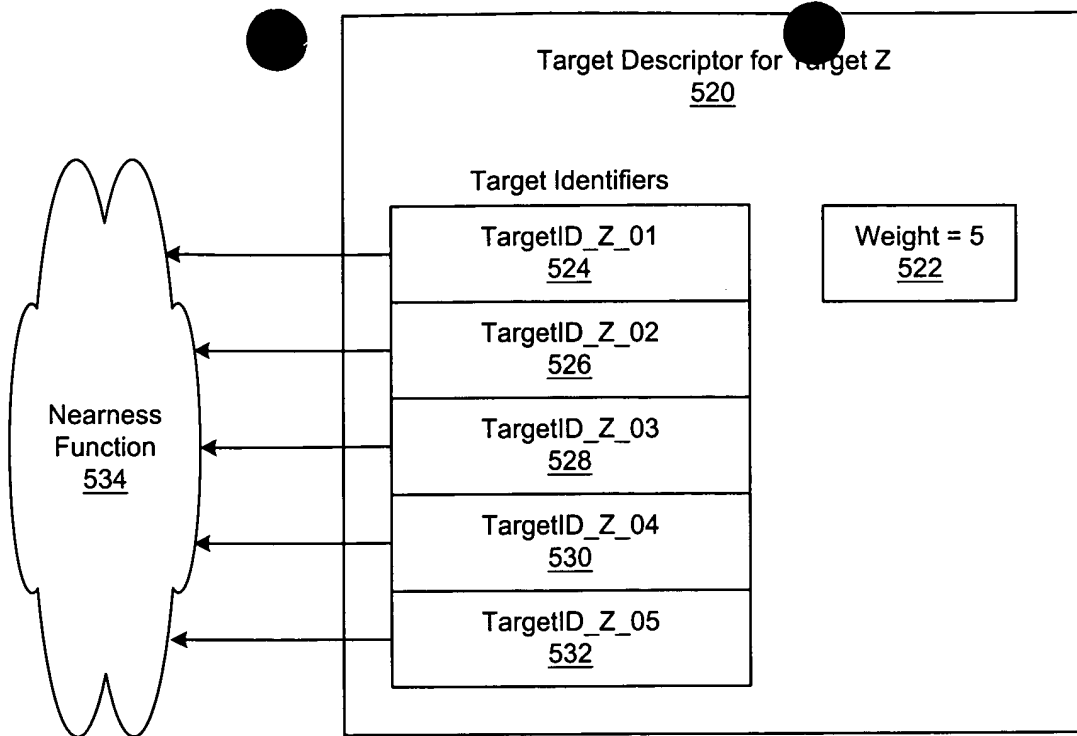


Figure 5C

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The flowchart illustrates the Nearest Neighbors Search Function (600). It begins with a 'targetMap index' (608) and a list of 'Target Identifier' entries (601, 602, 603, 604, 605). The 'targetMap index' (608) is processed by 'Hash Function 612' to produce a 'Hash Value' (616). Simultaneously, the 'Target Identifier' entries are processed by 'Hash Function 610' to produce 'Hash Values A-E' (614). Both 'Hash Value' (616) and 'Hash Values A-E' (614) are then processed by 'Hash Function 618' to produce 'Nearness Values A-E' (620). These values are compared by a 'Comparator' (622) to determine the 'Nearness Value for "nearest" Target X' (624).

12/12
AUS9-2000-0336-US1